

User manual METER SRP-73-XC

- Firmware: v.5.18 or higher
- Input type: 0-60/75/100/150 mV
- Two-colour display







Read the user's manual carefully before starting to use the unit or software. Producer reserves the right to implement changes without prior notice.

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Explanation of symbols used in the manual:



- This symbol denotes especially important guidelines concerning the installation and operation of the device. Not complying with the guidelines denoted by this symbol may cause an accident, damage or equipment destruction.

IF THE DEVICE IS NOT USED ACCORDING TO THE MANUAL THE USER IS RESPONSIBLE FOR POSSIBLE DAMAGES.



- This symbol denotes especially important characteristics of the unit.

Read any information regarding this symbol carefully

1. BASIC REQUIREMENTS AND USER SAFETY



- The manufacturer is not responsible for any damages caused by inappropriate installation, not maintaining the proper environmental conditions and using the unit contrary to its assignment.
- Installation should be conducted by qualified personnel. During installation all available safety requirements should be considered. The fitter is responsible for executing the installation according to this manual, local safety and EMC regulations.
- GND input of device should be connected to PE wire;
- The unit must be properly set-up, according to the application. Incorrect configuration can cause defective operation, which can lead to unit damage or an accident.
- If in the case of a unit malfunction there is a risk of a serious threat to the safety of people or property additional, independent systems and solutions to prevent such a threat must be used.
- The unit uses dangerous voltage that can cause a lethal accident. The unit must be switched off and disconnected from the power supply prior to starting installation of troubleshooting (in the case of malfunction).
- Neighbouring and connected equipment must meet the appropriate standards and regulations concerning safety and be equipped with adequate overvoltage and interference filters.
- Do not attempt to disassemble, repair or modify the unit yourself. The unit has no user serviceable parts. Defective units must be disconnected and submitted for repairs at an authorized service centre.



- In order to minimize fire or electric shock hazard, the unit must be protected against atmospheric precipitation and excessive humidity.



- Do not use the unit in areas threatened with excessive shocks, vibrations, dust, humidity, corrosive gasses and oils.

- Do not use the unit in areas where there is risk of explosions.

- Do not use the unit in areas with significant temperature variations, exposure to condensation or ice.
- Do not use the unit in areas exposed to direct sunlight.
- Make sure that the ambient temperature (e.g. inside the control box) does not exceed the recommended values. In such cases forced cooling of the unit must be considered (e.g. by using a ventilator).



The unit is designed for operation in an industrial environment and must not be used in a household environment or similar.

2. GENERAL CHARACTERISTICS

The **SRP-73-XC** meter is equipped with one voltage input 0-60 / 0-75 / 0-100 / 0-150mV. The selection of active input is realised by software, and selected input can be changed at any time. Additionally the **SRP-73-XC** allows user to select a conversion characteristic of several kinds: linear, square, square root, and user defined (max.20 points length). Result is showed on 4-digit LED display. Displayed values range can be selected by user, from -999 to 9999, plus decimal point.

The device can be equipped with one or two relay (or OC type) outputs. Device **SRP-73-XC** is equipped with RS-485 / Modbus RTU communication interface and sensor supply output. The meter can be ordered in two power supply versions.

SRP-73-XC can be used for controlling and regulation of processes need proportional and threshold control like: temperature processes (heating or cooling), valves controlling or other.

3. TECHNICAL DATA

Power supply voltage (depending on version) External fuse (required) Power consumption	85 <u>230</u> 260V AC/DC; 50 ÷ 60 Hz (separated) or 19 <u>24</u> 50V DC and 16 <u>24</u> 35V AC (separated) T - type, max. 2 A max. 4.5 VA @ 85 ÷ 260V AC/DC max. 4.5 VA @ 16V ÷ 35V AC max. 4.5 W @ 19V ÷ 50V DC
Voltage input	0÷60 mV, 0÷75 mV, 0÷100 mV, 0÷150 mV
Voltage measurement accuracy	± 0,1% @ 25°C; ± one digit (for 0÷150 mV range)
Voltage input resistance	> 100 kΩ
Temperature stability	50 ppm / °C
Display range	-999 ÷ 9999, plus decimal point
Accepted prolonged input overload:	20%

Outputs			
relay: or OC-type: sensor power supply:	0, 1 or 2 NO, 1A/250V AC (cos φ = 1) 0, 1 or 2; 30mA / 30VDC / 100mW 24V +5%, -10% / max. 100 mA, stabilized		
Communication interface	RS 485, 8N1 and 8N2, Modbus RTU, not separated		
Baud rate	1200 bit/s ÷ 115200 bit/s		
Display (depending on version)	LED, 4 digit, 13mm height, two-colour (red and green) or (for IP 65 version) 5 digit, 9mm height, red		
Data memory	non-volatile memory, EEPROM type		
Protection level (depending on display size)			
	IP 65 (from front), optional version with panel cut-out sealing availableIP 20 (housing and connection clips)		
4 x 13mm version:	IP 40 (from front) IP 20 (housing and connection clips)		
Housing type Housing material Housing dimensions Mounting hole Assembly depth Panel thickness	panel NORYL - GFN2S E1 72 x 36 x 97 mm 66.5 x 32.5 mm min. 102 mm max. 5 mm		
Operating temperature Storage temperature	0°C to +50°C -10°C to +70°C		
Humidity Altitude	5 to 90% no condensation up to 2000 meters above sea level		
Screws tightening max. torque Max. connection leads diameter	0,5 Nm 2,5 mm²		
Safety requirements	according to: PN-EN 61010-1 installation category: II pollution degree: 2 voltage in relation to ground: 300V AC insulation resistance: >20M Ω insulation strength between power supply and input/output terminal: 1min. @ 2300V insulation strength between relays terminal: 1min. @ 1350V		
EMC	according to: PN-EN 61326-1		
	-		
/ I his is a class A unit. Ir	n a residential or a similar area it can cause radio		

This is a class A unit. In a residential or a similar area it can cause radio frequency interference. In such cases the user can be requested to use appropriate preventive measures.

4. DEVICE INSTALLATION

The unit has been designed and manufactured in a way assuring a high level of user safety and resistance to interference occurring in a typical industrial environment. In order to take full advantage of these characteristics installation of the unit must be conducted correctly and according to the local regulations.



- Read the basic safety requirements on page 3 prior to starting the installation.

- Ensure that the power supply network voltage corresponds to the nominal voltage stated on the unit's identification label.

- The load must correspond to the requirements listed in the technical data.

- All installation works must be conducted with a disconnected power supply.

- Protecting the power supply connections against unauthorized persons must be taken into consideration.

4.1. UNPACKING

After removing the unit from the protective packaging, check for transportation damage. Any transportation damage must be immediately reported to the carrier. Also, write down the unit serial number located on the housing and report the damage to the manufacturer.

Attached with the unit please find:

- user's manual,
- warranty,
- assembly brackets 2 pieces.

4.2. ASSEMBLY



- The unit is designed for mounting inside housings (control panel, switchboard) insuring appropriate protection against surges and interference. Metal housings must be connected to ground in a way that complies with the governing regulations.

- Disconnect the power supply prior to starting assembly.

- Check the connections are wired correctly prior to switching the unit on.



In order to install the unit, a 66.5 x 32.5 mm mounting hole (Figure 4.1) must be prepared. The thickness of the material of which the panel is made must not exceed 5mm. When preparing the mounting hole take the grooves for catches located on both sides of the housing into consideration (Figure 4.1). Place the unit in the mounting hole inserting it from the front side of the panel, and then fix it using the brackets (Figure 4.2). The minimum distances between the centre points of multiple units - due to the thermal and mechanical conditions of operation - are 91 mm x 57mm (Figure 4.3).

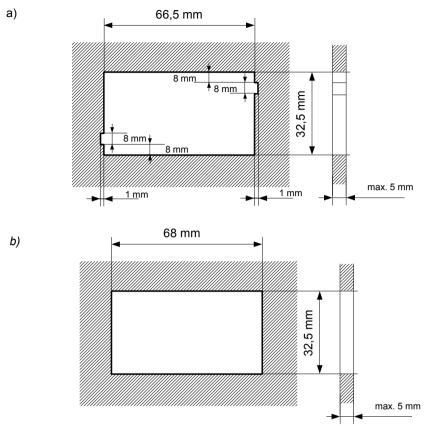


Figure 4.1. Mounting hole dimensions: a) recommended b) allowable

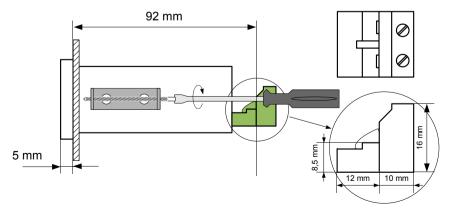


Figure 4.2. Installing of brackets, and dimensions of connectors.

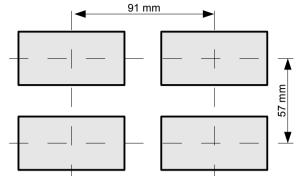


Figure 4.3. Minimum distances when assembly of a number of units

4.3. CONNECTION METHOD

Caution



- Installation should be conducted by qualified personnel . During installation all available safety requirements should be considered. The fitter is responsible for executing the installation according to this manual, local safety and EMC regulations.

- The unit is not equipped with an internal fuse or power supply circuit breaker. Because of this an external time-delay cut-out fuse with a small nominal current value must be used (recommended bipolar, max. 2A) and a power supply circuit-breaker located near the unit. In the case of using a monopolar fuse it must be mounted on the phase cable (L).

- The power supply network cable diameter must be selected in such a way that in the case of a short circuit of the cable from the side of the unit the cable shall be protected against destruction with an electrical installation fuse.

- Wiring must meet appropriate standards and local regulations and laws.

- In order to secure against accidental short circuit the connection cables must be terminated with appropriate insulated cable tips.

- Tighten the clamping screws. The recommended tightening torque is 0.5 Nm. Loose screws can cause fire or defective operation. Over tightening can lead to damaging the connections inside the units and breaking the thread.

- In the case of the unit being fitted with separable clamps they should be inserted into appropriate connectors in the unit, even if they are not used for any connections.

- Unused terminals (marked as n.c.) must not be used for connecting any connecting cables (e.g. as bridges), because this can cause damage to the equipment or electric shock.

- If the unit is equipped with housing, covers and sealing to, protecting against water intrusion, pay special attention to their correct tightening or clamping. In the case of any doubt consider using additional preventive measures (covers, roofing, seals, etc.). Carelessly executed assembly can increase the risk of electric shock.

- After the installation is completed do not touch the unit's connections when it is switched on, because it carries the risk of electrical shock.

Due to possible significant interference in industrial installations appropriate measures assuring correct operation of the unit must be applied. To avoid the unit of improper indications keep recommendations listed below.

- Avoid running signal cables and transmission cables together with power supply cables and cables controlling inductive loads (e.g. contactors). Such cables should cross at a right angle.
- Contactor coils and inductive loads should be equipped with interference protection systems, e.g. RC-type.
- Use of screened signal cables is recommended. Signal cable screens should be connected to the earthing only at one of the ends of the screened cable.
- In the case of magnetically induced interference the use of twisted pair of signal cables is recommended. Twisted pair (best if shielded) must be used with RS-485 serial transmission connections.
- In the case of measurement or control signals are longer than 30m or go outside of the building then additional safety circuits are required.
- In the case of interference from the power supply side the use of appropriate interference filters is recommended. Bear in mind that the connection between the filter and the unit should be as short as possible and the metal housing of the filter must be connected to the earth with the largest possible surface. The cables connected to the filter output must not be run with cables with interference (e.g. circuits controlling relays or contactors).

Connections of power supply voltage and measurement signals are executed using the screw connections on the back of the unit's housing.

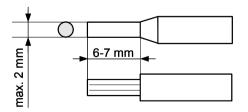


Figure 4.4. Method of cable insulation replacing and cable terminals

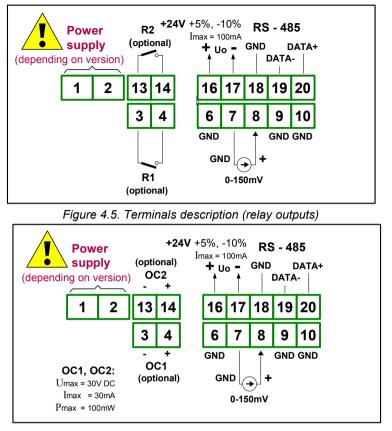


Figure 4.6. Terminals description (OC-type outputs)

All connections must be made while power supply is disconnected !

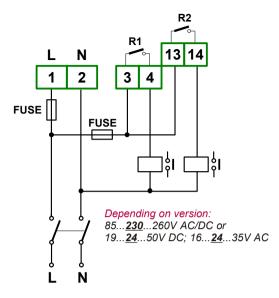


Figure 4.7. Connection of power supply and relays

Contacts of relay outputs are not equipped with spark suppressors. While use the relay outputs for switching of inductive loads (coils, contactors, power relays, electromagnets, motors etc.) it is required to use additional suppression circuit (typically capacitor 47nF/ min. 250VAC in series with 100R/5W resistor), connected in parallel to relay terminals or (better) directly on the load. In consequence of using the suppression circuit, the level of generated electromagnetic disturbances is lower, and the life of relay contacts rises.

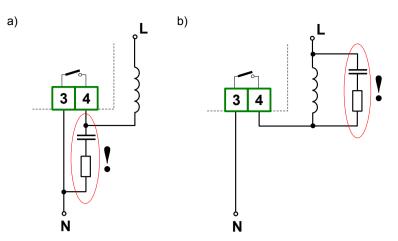


Figure 4.8. Examples of suppression circuit connection: a) to relay terminals; b) to the inductive load

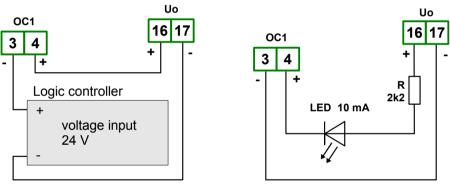


Figure 4.9. Example of OC-type outputs connection

4.4. MAINTENANCE

The unit does not have any internal replaceable or adjustable components available to the user. Pay attention to the ambient temperature in the room where the unit is operating. Excessively high temperatures cause faster ageing of the internal components and shorten the fault-free time of the unit's operation.

In cases where the unit gets dirty do not clean with solvents. For cleaning use warm water with small amount of detergent or in the case of more significant contamination ethyl or isopropyl alcohol.

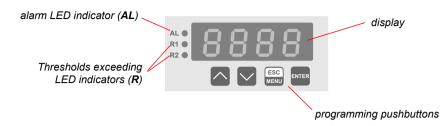


Using any other agents can cause permanent damage to the housing.

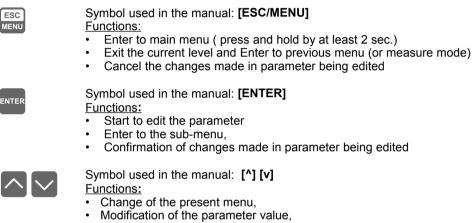


Product marked with this symbol should not be placed in municipal waste. Please check local regulations for disposal of electronic products.

5. FRONT PANEL DESCRIPTION



Symbols and functions of push-buttons:



· Change of the display mode.

6. PRINCIPLE OF OPERATION

After turning the power supply on, device ID and software version are showed on the display, next the controller goes to the measurement mode.

6.1. MEASUREMENT MODE

In the measure mode, the measurement results, converted over selected characteristic, are displayed on the LED display. The measurement range equal to the nominal range is called: *nominal measurement range*, and the measurement range equal to the extended nominal range is called: *permissible measurement range* (Figure 6.1).

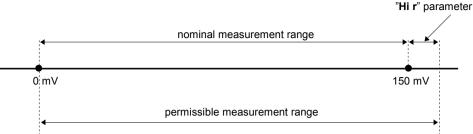


Figure 6.1. Definitions of measurement ranges in mode 0 ÷ 150mV

If the result of measurement exceeds the *permissible measurement range*, warning "-Hi-" or "-Lo-" is displayed rather than input signal, depends on exceeded value (see description of "Hi r" parameter, paragraph "*inPt*" menu).

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If the measurement value do not exceeds *permissible measurement range* but displayed value exceeds range -999 \div 9999, the warning "**-Ov-**" is displayed rather than the calculated result.

In the measurement mode user can check main thresholds values. After pressing [^] or [v] button, name of the threshold (e.g. "rEL1") and his value will be displayed on the display in alternating mode. If [^] or [v] will be pressed in 5 sec again, the next threshold will be displayed, else the device comes back to the measurement mode. If a *free access* is enabled (see description of "SECu" menu), user can change the value of particular threshold pressing button [ENTER] (see: PARAMETERS EDITION).

Input type, range of displaying values, characteristic of conversion, decimal point position and measure filtering ratio, are user configurable parameters. All accessible parameters can be changed by entering the menu (see: **DEVICE PROGRAMMING**). Use the local keyboard or the remote controller to do it. (Note: all parameters can be remote changed via RS-485 interface).

Configuration of the device (via menu or RS-485 interface) <u>do not stops measures</u>.

6.2. DETECTION OF THE PEAK VALUES

The **SRP-73-XC** controller is equipped with peaks detection function. It can detect a peaks of the input signal and display their values. Presets connected with this function are placed in "**HOLd**" menu (see description of "**HOLd**" menu). The detection of the peak can be done if the measured signal raises and drops of value at least equal to parameter "**PEA**". Detected peaks are displayed during the time defined by parameter "**timE**". If a new peak will be detected while one is displayed, this new peak will be displayed and display time counter will be cleared (Figure 6.2). If no peaks are detected while time "**timE**" elapses, device starts to show the current value of input signal again. If "**HdiS**"="**HOLD**" then setting parameter "**timE**"=0.0 causes holding peak value until **[ESC]** button is pressed. If "**HdiS**"="**rEAL**" then value "**timE**"=0.0 means no holding. Displaying peak value is signalized by flashing most right decimal point.

The relays/LEDs can be controlled depend on the current value of input signal or the peak value (see "*HOLd*" *menu*).

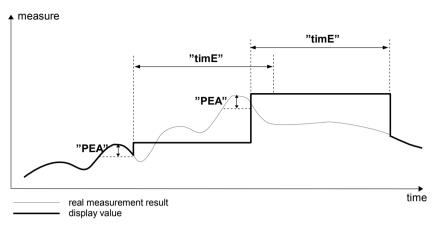


Figure 6.2. Process of peaks detection

6.3. CONTROL OF THE RELAY OUTPUTS

The control of the object (measured signal) is realized via relay outputs. Front panel LEDs named $_{R}$ " indicates the state of particular relay output.

If device is not equipped with one or more relay outputs, menus refer to this relays are available, but apply to LED indicators only. In such case LEDs indicates exceeding of particular thresholds.

Modes of the control can be changed depend on the values of parameters "SEtP", "SEt2", "HYSt", "modE", "t on", "toFF", "unit" and "AL". Depend on "modE" parameter, relays can be not used or controlled over one or two thresholds values.

If one threshold is used (Figure 6.3) the relay can be turned on ("**modE**" = "**on**") or off ("**modE**" = "**oFF**") when the input signal value is contained in *zone A*. If two thresholds are used (Figure 6.4) the relay will be turned on when value of input signal is contained in *zone A* ("**modE**" = "**in**") or *zone B* ("**modE**" = "**out**") and turned off if the signal is contained in the second one.

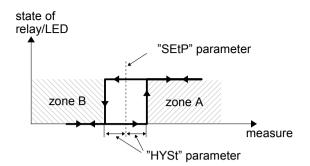


Figure 6.3. One threshold control of the relay/LED outputs

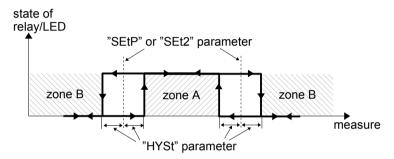


Figure 6.4. Two threshold control of the relay/LED outputs

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The relay outputs and LEDs (named \mathbf{R}) can be controlled depend on both - the current value and the peak value (when peak detection is active) of the input signal.

6.3.1. One threshold mode

Figure 6.5 presents the principle of relay outputs operation for one threshold mode, and an example values of other parameters.

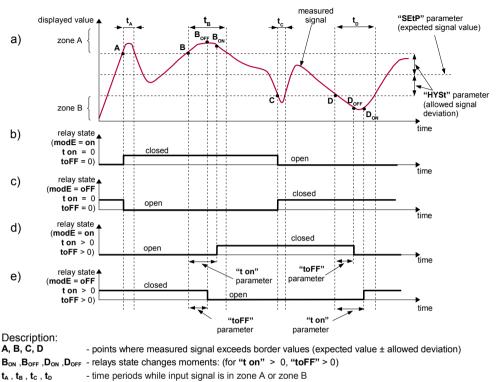


Figure 6.5. Principle of LED/relay output operation for one threshold mode

Parameter **"SEtP**" sets a **threshold** of the relay, and parameter **"HYSt**" sets a **hysteresis** of the relay (Figure 6.5 a). The relay can change his state <u>only</u> when input value exceeds (over or under) **border value** and t_A , t_B , t_C , t_D times (Figure 6.5) are bigger than the time defined by parameters **"t on"**, **"toFF"** and **"unit"**. **Border values** means values equal **threshold+hysteresis** and **threshold-hysteresis** respectively.

If "t on" and "toFF" parameters are set to "0", then the relay state will be changed <u>as soon</u> as input value exceeds any of the *border values* (see points A and C, Figure 6.5 a, b, c).

If values of "t on" or/and "toFF" are positive, then relay state will be turned on if the input value exceeds the *border values* and stay bigger (or lower) during at least

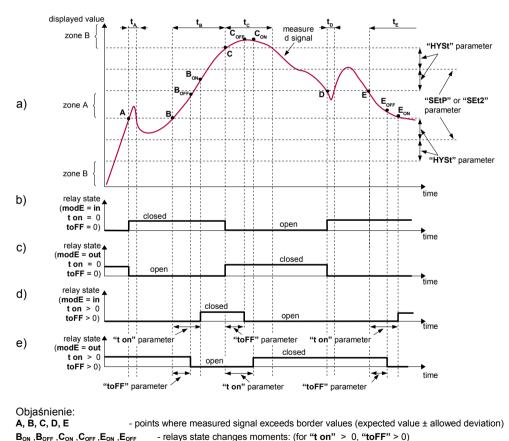
"t on" (see points B_{ON} , D_{ON} , Figure 6.5 a, d, e). Similarly, the relay will be turned off if time "toFF" elapse since the input signal value exceeds any of the *border values* (see points B_{OFF} , D_{OFF} , Figure 6.5 a, d, e).

If t_A , t_B , t_C or t_D (when input signal stay in *zone A* or *zone B*) are lower than parameters "t on" or "toFF", the relay will not change his state (see points A and C, Figure 6.5 a, d, e).

The state of relay output while the input value exceeds the **border values** (points A, B, C, D) is described by parameter "**modE**". The relay can be turned on ("**modE**" = "**on**"), or turned off ("**modE**" = "**oFF**") when input signal value is contained in **zone** *A* (Figure 6.5 a).

The parameter "AL" allow user to set the relay output behaviour in critical situations (e. g. Input values exceeds *permissible measurement range*). User can select that the relays will be turned on, turned off, or not changed in critical situations.

All parameters connected with relay outputs are described in paragraph "rEL1" menu.



6.3.2. Two thresholds mode

t_E - time periods while input signal is in zone A or zone B
 Figure 6.6. Principle of LED/relay output operation for two thresholds mode

 t_A , t_B , t_C , t_D , t_E

Figure 6.6 presents the principle of relay outputs operation for two thresholds mode, and an example values of other parameters. In this mode parameter **"SEt2"** is accessible in common with **"SEtP"**, this parameter describes a second threshold of the relay output. The parameters **"HYSt"**, **"modE"**, **"t on"**, **"toFF"**, **"unit"** and **"AL"** are connected with both **"SEtP"** and **"SEt2"** thresholds. While the controlling process, the relay output changes his state depends of both **"SEtP"** and **"SEt2"** thresholds in similar way as it was described in one threshold mode.

If two threshold mode is used, "**modE**" parameter defines state of the relay output when the input value occurs in a particular zone defined by **border values** of both **thresholds**. The relay can be turned on if the input value is contained in **zone A** ("**modE**" = "**in**") or **zone B** ("**modE**" = "**out**") and turned off if it is contained in the second one (Figure 6.6).



The sequence of thresholds "SEtP" and "SEt2" can be set in any order, due to the control of relay outputs is done depend on difference between thresholds values (zone A) and outside of threshold values (zone B).

7. DEVICE PROGRAMMING

The device menu allow user to set all parameters connected to operation of measurement input, control modes, critical situations behaviour, communication via RS-485 and access settings. The meaning of the particular parameters is described in paragraph **MENU DESCRIPTION**.

Some of the parameters can be accessed without menu entering (quick view mode). After pressing [^] or [v] button, name of the threshold (e.g. "rEL1") and his value will be displayed on the display in alternating mode. If [^] or [v] will be pressed in 5 sec again, the next threshold will be displayed, else the device comes back to the measurement mode. If a *free access* is enabled (see description of "SECu" menu), user can change the value of particular threshold pressing button [ENTER] (see: PARAMETERS EDITION).



If particular parameter has been changed and confirmed in quick view mode, its new value is displayed in alternating mode with parameter name by few seconds. Confirmed changes may be checked or user can switch viewed parameter pressing [^] or [v] button.

7.1. PROGRAMMING MENU

To enter main menu (being in the measurement mode) operator must to press and hold at least 2 sec. **[ESC/MENU]** button.

If the user password is defined (see parameter "Scod", menu "SECU"), operator have to enter correct one before proceeding to menu options. Entering of the passwords is similar to the edition of numeric parameters (see: **PARAMETERS EDITION**), however presently editing digit is showed only on the display, other digits are replaced by "-" sign.

After entering of last digit of the password first menu position will be displayed (if the password is correct) or warning "**Err**" in other case.



Pay attention when device parameters are being changed. If it is possible, turn off controlled installation (machine).

Functions of the buttons while sub-menu and parameters choice:



Selection of sub-menu or parameter for editing. Name of selected item (submenu or parameter) is displayed.

Operation of [ENTER] button depend on present menu position:

- if the name of some sub-menu is displayed enter this sub-menu; name of the first parameter (or next level sub-menu) is displayed,
- if the name of some parameter is displayed enter the edition of this parameter; present value of the parameter is displayed,



INTER

[ESC/MENU] button allow user to exit present menu level and goes to upper level menu (or measurement mode).

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After about 1 min. since last use of the buttons, device exits the menu mode and returns to the measurement mode (only if no parameters are in editing mode).

7.2. PARAMETERS EDITION

To start edition of any parameter user should select name of desired one using [^] [v] buttons and then press [ENTER].

7.2.1. Numeric parameters (digit change mode)

Numerical parameters are displayed as decimal numbers. The mode of its new value entering depends on chosen edit method (see parameter **"Edit**").

In mode "by digit" ("**Edit**"="dig") pressing one of the keys [^] or [v] causes change of current position (flashing digit) or the sign (+/-). Short pressing of the [ENTER] button causes change of the position (digit).

Press [ENTER] at least 2 seconds to accept the changes, after that question "SEt?" is displayed, and user must to confirm (or cancel) the changes. To conform changes (and story it in EEPROM) press [ENTER] button shortly after "SEt?" is displayed. To cancel the changes press [ESC] button shortly after "SEt?" is displayed. After that device returns to the menu.

7.2.2. Numeric parameters (slide change mode)

In "slide change" mode ("Edit"="Slid"), buttons [^] and [v] has different functions.

To increase edited value press (or press and hold) [^] button only, the increasing became quickest as long as button [^] is pressed. To slow down the increasing, button [v] can be used. If [v] is pressed shortly (and button [^] is still pressed), increasing slow down for a moment only, if [v] is pressed and held while button [^] is still pressed the increasing slow down and will be kept on lower speed.

To decrease edited value press (or press and hold) **[v]** button only. The decreasing became quickest as long as button **[v]** is pressed. To slow down the decreasing, button **[^]** can be used. If **[^]** is pressed shortly (and button **[v]** is still pressed), decreasing slow down for a moment only, if **[^]** is pressed and held while button **[v]** is still pressed the decreasing slow down and will be kept on lower speed.

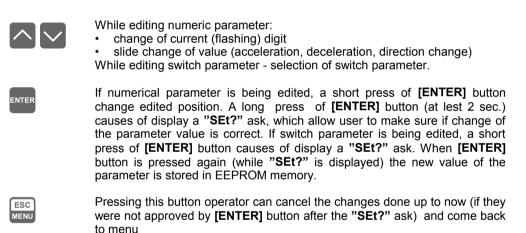
Press **[ENTER]** at least 2 seconds to accept the changes, after that question "Set?" is displayed, and user must to confirm (or cancel) the changes. To conform changes (and story it in EEPROM) press **[ENTER]** button shortly after "SEt?" is displayed. To cancel the changes press **[ESC]** button shortly after "SEt?" is displayed. After that device returns to the menu.

7.2.3. Switch parameters ("LIST" type)

Switch parameters can be described as a sets of values (a lists) out of which only one of the options available on the list can be selected for the given parameter. Options of switching parameter are selected using [^], [v] keys.

Short pressing of **[ENTER]** causes in displaying of the acknowledge question ("SEt?"). If key **[ENTER]** is pressed again, the changes are accepted, stored in EEPROM end the edition process finished. Pressing the key **[ESC]** after "SEt?" causes in cancelling of made changes and returning to menu.

Functions of buttons when editing numeric and switching parameters:



7.3. MENU DESCRIPTION

"---" - password checking. If some password different from "**0000**" is set, then every enter to main menu follows the entering of password. If entered password is correct then first menu position will be displayed else warning "**Err**", and unit returns to measurement mode.



Due to problem with direct displaying of "**m**" and "**K**" letters, they are exchanged with special signs "**n**" for "m" and "**H**" for K respectively. However, in user manual letters "**m**" and "**K**" are used to make it more readable (example: "**modE**", "**tc K**").

7.3.1. "rEL1" menu

i

This menu allows to configure the operation mode of relays and LEDs marked "R" (e.g. "R1").

If there are few relay outputs available, then every output has its own configuration menu (e.g. menu **"rEL2**" for relay (LED) **"R2**"). Principle of the relays operation is described in paragraph *CONTROL OF THE RELAY OUTPUTS*.

- The relay outputs and LEDs (named R) can be controlled depend on both the current value and the peak value (when peak detection is active) of the input signal.
 - If device is not equipped with one or more relay outputs, menus refer to this relays are available, but apply to LED indicators only. In such case LEDs indicates exceeding of particular thresholds.
- "SEtP" first threshold of the relay (range -999 ÷ 9999). Negative values can be input by selecting a "-" sign on first digit (to change value use [^] and [v] buttons). Threshold is the medium value of relay hysteresis.
- "SEt2" second threshold of the relay (range -999 ÷ 9999). Negative values can be input by selecting a "-" sign on first digit (to change value use [^] and [v] buttons). This threshold is accessible when "modE" parameter is set to "in" or "out" value. Threshold is the medium value of relay hysteresis.
- "HYSt" hysteresis of relay (range 0 ÷ 999). Full hysteresis of the relay is equal to 2x
 "HYSt" parameter. The relay state can change when an input signal is out of threshold-hysteresis to threshold+hysteresis zone.
 - Presented parameters should be set to ensure that "SEtP" + "HYSt", "SEt2" + "HYSt", "SEtP" - "HYSt" or "SEt2" - "HYSt" do not exceeds the measure range. Additionally, in two threshold mode ("modE"= "in" or "out"), the hysteresis for both thresholds must not cover each other (in other case relay can't change his state).
- "modE" relay operation mode:
 - "noAC" the relay is not active (permanent turned off)
 - "on" one threshold mode, the relay is turned ON when input signal exceeds SEtP + HYSt value, and is turned off back when the input signal became lower than SEtP – HYSt,
 - "oFF" one threshold mode, the relay is turned OFF when input signal exceeds SEtP + HYSt value, and is turned on back when the input signal became lower than SEtP – HYSt,
 - "in" two threshold mode, the relay is turned ON when the input signal is bigger than "*lower threshold* + HYSt" and lower than "*bigger threshold* HYSt", and turned off when the input signal is contained in the second zone. The *bigger threshold* means bigger one of "SEtP" and "SEt2" thresholds, the *lower threshold*" means lower one of "SEtP" and "SEt2" thresholds.

- "out" two threshold mode, relay is turned ON when the input value is bigger than "bigger threshold + HYSt" and lower than "lower threshold – HYSt", and turned on when the input signal is contained in the second zone. The bigger threshold means bigger one of "SEtP" and "SEt2" thresholds, the lower threshold" means lower one of "SEtP" and "SEt2" thresholds.
- *"modb"* the relay is controlled via RS-485 interface, independently on the input signal.
- LEDs light when relays are closed, independently of relays' mode.
- When power supply fail, unit do not store relays state selected by RS-485 interface.
- "t on" turn on delay time, the relay is turned on with delay equal "t on" if the input value exceeds appropriate *border value* (defined with *threshold* and *hysteresis*), at least "t on" time. "t on" range 0 ÷ 99.9, defined with 0.1 sec. resolution. Unit of this parameter is set by "unit" parameter.
- "toFF" turn off delay time, the relay is turned off with delay equal "toFF" if the input value exceeds appropriate *border value* (defined with *threshold* and *hysteresis*), at least "toFF" time. "toFF" range 0 ÷ 99.9, defined with 0.1 sec. resolution. Unit of this parameter is set by "unit" parameter.



If time when the input signal exceeds some border value is shorter than "t on" or "toFF" time, the relay do not change his state (see paragraph: *CONTROL OF THE RELAY OUTPUTS*).

"unit" - unit of time for "t on" i "toFF" parameters. Can be set on one of two values:

"min"	- minutes,
"SEC"	- seconds.

"AL" - this parameter defines the relay reaction when some critical situations occurs:

"noCH" - relay do not change his state,
"on" - relay will be turned on,
"oFF" - relay will be turned off.

If parameter **"modE"** is set to **"on"**, **"oFF"**, **"in"** or **"Out"** the "critical situation" means that allowable measurement range is exceeded.

If parameter "modE" is set to "modb", the "critical situation" means communication delay (when no data is received) longer than "mbtO" parameter (see description: "*rS" menu*).

If option "noCH" is selected for "AL" parameter, behaviour of the relay may depend on "FiLt" parameter in some cases. If "FiLt" is set to big value and the input signal drops, result value of the measure will change slow, causes of turning on or off relay due to thresholds values. The critical situation is slowly detected, so it is impossible to predict the relay state in that situations.

 If parameter "AL" = "on", the relay will be turned on in the critical situations, even if his parameter "modE" = "noAC".

7.3.2. "inPt" menu

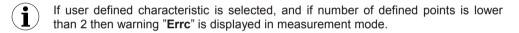
This menu presets the measurement input:

 "tYPE" - type of the input / sensor. This parameter can be set to values:
 "60", "75", "100", "150" - voltage inputs expressed in mV. Displayed values are defined by parameters "Lo C", "Hi C" (or by user defined characteristic points) and parameter "Pnt".

"CHAr" - this option presets type of the conversion characteristic, and can be set to:

"Lin"	- linear	
"Sqr"	- square	When one of those characteristics is chosen display
"Sqrt"	 square root 	range is defined by "Lo C" and "Hi C".

"USEr" - user defined characteristic. Maximal length 20 points. Every point is defined by user. Adding, Editing and Deleting of points is done by options **"AddP**", **"EdtP**", **"dELP**" (**"InPt**" menu) respectively.



The process of displayed result calculation is described in details in **DISPLAY VALUES CALCULATION** paragraph.

- "FiLt" this parameter sets filtration rate. It can be set to values from 0 (no filtration) to 5 (strongest filtration time window about 2 sec).
- "Pnt" decimal point position. It can be set to one of:
 "0", "0.0", "0.00", "0.000"
 Decimal point position is changed by [^], [v] buttons.
- "Lo C" These parameters describe the values displayed for minimum and maximum input "Hi C" current. For example, if input type is set to 4-20 mA "Lo C" parameter defines the value displayed when input current is equal 4 mA, and "Hi C" parameter defines the value displayed for 20 mA of input current. Available range for these parameters: -999 ÷ 9999. Negative values can be set by entering '-' sign on the first position (by use of [^], [v] buttons).



If user defined characteristic is selected (parameter "CHAr" = "USEr") the parameters **"Lo C**" and **"Hi C**" are not available for modification, due to their values are calculated from defined characteristic.

"AddP" - this menu allow user to add single point to the user defined characteristic. After selection of this option device waits for "X" and "Y" coordinates of new point. Modification of the coordinates is done accordingly to numerical parameters edition. Coordinate **"X**" defines the percentage ratio of input current to selected current range. The **"X**" range: $-99,9 \div 199,9$. Coordinate **"Y**" defines displayed value for particular **"X**" value. The **"Y**" value can be changed in range: $-999 \div 9999$, decimal point position depend on **"Pnt**" parameter (menu **"inPt**").

- (\mathbf{i})
- User can not enter two points with the same value of "X" coordinate. If user trays to do it, "Err" warning is displayed. To modify any defined point use "EdtP" option.
 - To distinguish **"X**" and **"Y**" coordinates, if **"X**" coordinate is displayed an additional decimal point on utmost right position is displayed.
 - If user defined characteristic is selected, and if number of defined points is lower than 2 then warning "Errc" is displayed in measurement mode.
- "dELP" this option allows user to delete any of the points of the user defined characteristic. After selection current number of points of the user defined characteristic is displayed for about approx. 1.5 sec. After that device waits for selection of point being deleted (by [^], [v] buttons). The short pressing of [ENTER] button causes by switching between X and Y value of the displayed point. The long press (press and hold at least 2 sec) of [ENTER] button causes by displaying "dEL?" ask. If [ENTER] button is pressed again, current point is deleted and new updated number of points of the user defined characteristic is displayed.
- "EdtP" this option allows user to modify of particular point of the user defined characteristic. After selection current number of points of the user defined characteristic is displayed for about approx. 1.5 sec. After that device waits for selection of point being edited (by [^], [v] buttons). The short pressing of [ENTER] button causes by switching between X and Y value of the displayed point. The long press (press and hold at least 2 sec) of [ENTER] button causes by entering to edit the selected coordinate of the point. Modification of the coordinates is done accordingly to numerical parameters edition.

"AddP", "dELP" and "EdtP" options are available only if the user defined characteristic is used (it means when parameter "CHAr" = "USEr").

"Hi r"

- this parameter define the expansion of nominal range in percent. It determine the permissible range of input signal (Figure 7.1).

The permissible range allow user to exceed the *nominal range* of input signal. If input value is contained in the permissible range a proper result is displayed. If input signal exceeds this range (defined by "**Hi r**"), "**-Lo-**" or "**-Hi-**" warning is displayed depend on input signal value.

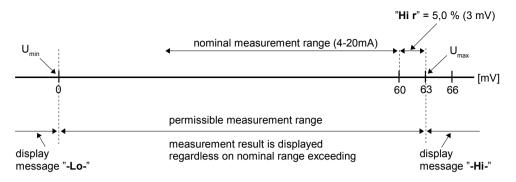


Figure 7.1 Example of definition of permissible range of input signal -"**Hi r**" parameter ("**60**" mode)

Parameter "**Hi r**" determines the upper border of the permissible range accordingly to the expression (for all modes).

For example if input is set to "**60**" mode, then upper border is calculated due to expression: $U_{max} = 60 \text{ mA} + 60 \text{ mA} \times "Hi r" \%$. The value of "**Hi r**" can be set from 0 to 19.9%

In example no 1 of the **DISPLAY VALUES CALCULATION** paragraph the procedure of the permissible input range determining is presented in details.



If the measurement value do not exceeds *permissible measurement range* but displayed value exceeds range -999 ÷ 9999, the warning "**-Ov-**" is displayed rather than the calculated result.

7.3.3. "bri" parameter

This parameter allows user to set bright of the LED display, bright can be set to conventional values from 1 to 8.

7.3.4. "CoL" menu

This menu contains settings related to signalisation via display colour. This kind of signalisation consist in change of display colour (from basic colour to "active" colour) in defined situations, for example after change of R1 state.

"SCoL" - basic colour (the second one becomes "active" colour):

- "grEE" main colour is green,
- "rEd" main colour is red.
- "C r1", "C r2" control the display colour according to relay (R1, R2 separate)state :

"oFF" - control for particular relay is off,

- "on" control for selected relay is on, the display will change its colour after selected relay becomes active.
- "C AL" control the display colour according to alarm situations :

"oFF" - control is off,

- "on" control is on, the display will change its colour after alarm situation occurs.
- "C Pr" this setting enables additional threshold for display colour controlling, detailed conditions of this control are defined by "dir", "SEtP" and "HySt" parameters of "CoL" submenu.

"oFF" - no additional threshold.

- "on" additional threshold enabled, the display will change its colour after result satisfy conditions defined by "dir", "SEtP" and "HySt" parameters of "CoL" submenu.
- "dir" this parameter defines the direction of result changes activating change of display colour:
 - "morE" display will change its colour after the result is higher than threshold +hysteresis
 - "LESS" display will change its colour after the result is lower than threshold + hysteresis
- "SEtP" additional threshold value (range -999 ÷ 9999). Negative values can be input by selecting a "-" sign on first digit (to change value use [^] and [v] buttons). Threshold is the medium value of relay hysteresis.
- "HYSt" Hysteresis of colour indication (range 0 ÷ 999). Full hysteresis is equal to 2x
 "HYSt" parameter. The display colour can change when an input signal is out of threshold-hysteresis to threshold+hysteresis zone.



Presented parameters should be set to ensure that "SEtP" + "HYSt" and "SEtP" - "HYSt" do not exceeds the measure range.

- "CrES" permission to use any local key to acknowledgement of display colour change. Acknowledgement causes clear of all events generating display colour changes (to active colour), and restores basic colour of the display.
 - "oFF" acknowledgement disabled,
 - "on" acknowledgement enabled.

7.3.5. "HOLd" menu

This menu contains parameters connected with peak detection function. See also full description of the peak detection function in paragraph: **DETECTION OF THE PEAK VALUES**

"modE" - the type of detected changes of the input signal, can be set to values:

"norm" - peaks, peak and next drop of the input signal of value equal at least "**PEA**", *"inv"* - drops, drop and next peak of the input signal of value equal at least "**PEA**",

- **"PEA"** minimal detected signal change classified as peak or drop (see Figure 6.2)
- "timE" maximum time of displaying of the peak (drop) value, can be set from 0.0 to 19.9 sec, with 0.1 sec. resolution. If "HdiS"="HOLD" then setting parameter "timE"=0.0 causes holding peak value until [ESC] button is pressed. If "HdiS"="rEAL" then value "timE"=0.0 means no holding.
- "HdiS" type of displayed values:
 - "rEAL" current value is displayed,
 - "HOLd" peak (drop) value is displayed,

"H r1", "H r2" - relay/LED outputs (R1, R2) operation mode:

"**rEAL**" - relay/LED operates depend on the current value, "**HOLd**" - relay/LED operates depend on the peak (drop) value.

7.3.6. "SECu" menu

This menu contains presets connected with availability of other parameters:

"Scod" - user password (4-digits number). If this parameter is set at value "0000", user password is turned off.

If the user do not remember his password, the access to the menu is possible by the "one-use password". To get this password please contact with Marketing Division. "Single use password" can be used only one time, after that it is destroyed. Entering this password causes in clearing of user password, it means sets the user password to "0000".



The "one-use password" can be used **ONE TIME ONLY**, it is impossible to use it again! The "one-use password" can be restored by Service Division only.

"A r1, A r2" - this option permits user ("on") or prohibits ("oFF") to modify the thresholds of the relays/LEDs R1, R2 without knowledge about user password.

<u>7.3.7. "rS" menu</u>

This menu is connected with RS-485 interface, and sets his properties:

"Addr" - this parameter defines the address of the device, accordingly to Modbus protocol. It can be set in range from 0 to 199. If the value 0 is set then device, responds to frames with address 255 (FFh).

- "bAud" this parameter determines RS-485 interface baud rate. It can be set to one of 8 possible values: "1.2", "2.4", "4.8", "9.6", "19.2", "38.4","57.6","115.2", which respond to the baud rates of 1200, 2400, 4800, 9600, 19200, 38400, 57600 and 115200 bit/s respectively.
- **"mbAc"** this parameter sets the access to the configuration registers of the device. Possible values:
 - "on" configuration registers can be set via RS-485 interface,

"**oFF**" - configuration registers can not be set via RS-485 interface.



The access to registers no 04h i 05h cant be denied by "mbAc" parameter (see: *LIST OF REGISTERS*).

- "mbtO" this parameter defines maximal time (sec) between following frames received by the device. If the delay will be greater than the value of "mbtO" parameter, the relays which are controlled via RS-485 interface, will set to alert state (see "rEL1" menu description). Parameter "mbtO" can be set to values from 0 to 99 seconds. The value 0 means that the time will be not controlled.
- "rESP" this parameter defines minimal (additional) delay between the Modbus message and the answer of the device (received and sent via RS-485 interface). This additional delay allows the device to work with poor RS-converters which do not works properly on baud rates higher than 19200. This parameter can be set to one of values:
 - "Std" answer as quick as possible, no additional delay
 - " 10c" " 20c" " 50c" "100c"

"200c"

- answer delayed of 10, 20, 50, 100 of 200 chars respectively, where one character time depends on selected baud rate



In the most cases parameter "**rESP**" should be set to "**Std**" (no additional delay). Unfortunately for some third party RS-converters "**rESP**" should be adjusted experimentally. Table 7.1 contains most frequently used values.

"bAud" parameter	"38.4"	"57.6"	"115.2"
"rESP" parameter	" 10c"	" 20c"	" 50c"

Tab.7.1.	Settings of	"rESP"	parameter
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7.3.8. "Edit" parameter

This parameter allows to change the edition mode of numerical parameters:

"dig" - the change to "by digit" mode,

"Slid" - slide change mode.

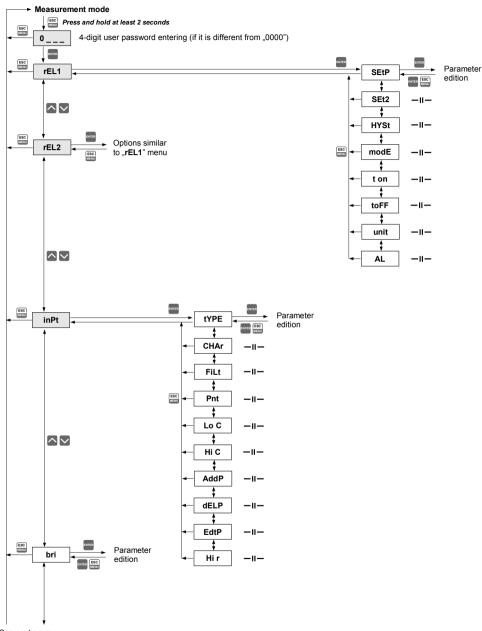
7.3.9. "dEFS" parameter

This setting allows to restore the factory settings of the device. To get the access to this option special password is required: "5465", next the device displays acknowledge question "SEt?". Press [ENTER] to acknowledge the restoring of factory settings or [ESC] to cancel.

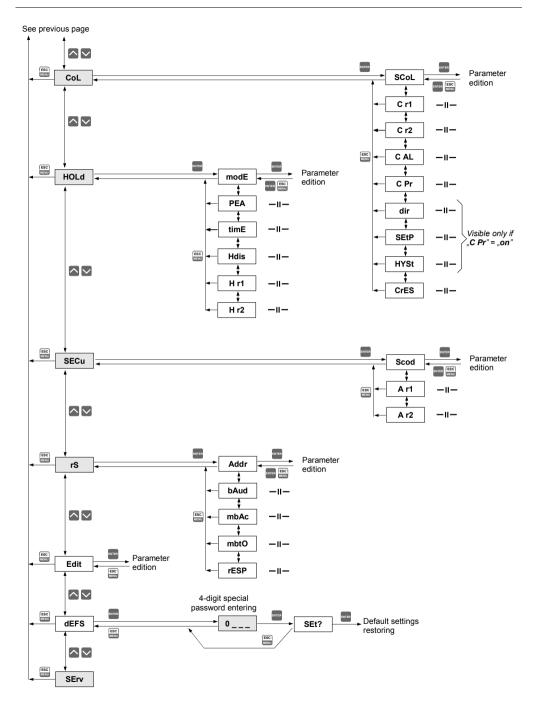
7.3.10. "SErv" menu

This menu contains the parameters for authorized service only. To enter this menu proper service password must be entered. Improper settings can causes of damage of the device.

7.4. MENU STRUCTURE



See next page



8. THE ALARM LED

The ALARM LED (AL) is turned on when input signal is out of the permissible input range. See parameters: "tyPE" and "Hi r" in paragraph "InPt" menu.

9. DISPLAYED VALUES CALCULATION

The first step to compute the result of measure is the calculation of the normalized result (it means result of 0-1 range). To do it, the begin of the input range (0 mV) must be subtracted from measured value. Next, received result must be divided by the width of the input range (it means 100 for 0-100mV range). So normalized result can be expressed by expression:

$$U_n = \frac{U_{inp.}}{100} \qquad \qquad for \quad 0 \div 100 \, mV \quad range$$

where U_{inp.} Means input voltage (in mV), and U_n - normalized result.



If measured value exceeds the nominal input range (60mV, 75mV, 100mV or 150mV), and do not exceed the permissible input range, then received normalized U_n result will exceed 0-1 range, e.g. input range 0-100 mV, input voltage = 1 mV – the normalized result is equal -0,01, and for input voltage = 110 mV, the normalized result is equal 1,1. In such cases presented expressions are still correct.

9.1. ADDITIONAL CALCULATIONS (USED CONVERSION CHARACTERISTIC)

The manner of the additional computation of the displayed result depends on selected conversion characteristic. All presented charts are connected with the input range 0 - 100 mV.

9.1.1. Linear characteristic

The normalized result is converted by fixed coefficients determined by "Lo C" and "Hi C" parameters (when the normalized results is equal 0, then value "Lo C" is displayed, and when the normalized results is equal 1, then value "Hi C" is displayed). Expression presented below shows the manner of result calculation:

$$W = U_n \times ("Hi C" - "Lo C") + "Lo C"$$

where W means the displayed value.



The value of the "Lo C" parameter can be higher than the value of "Hi C" parameter. In such a case, for an increasing value of input voltage the displayed value decreases.

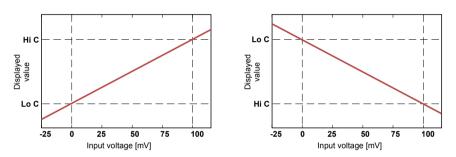


Figure. 9.1 Normal ("Lo C" < "Hi C) and inverted ("Lo C" > "Hi C) characteristic

9.1.2. Square characteristic

The normalized result is squared and further conversion is done as for linear characteristic. Conversion is made accordingly with the expression:

$$W = U_n^2 \times ("Hi C" - "Lo C") + "Lo C",$$

where W means the displayed value.

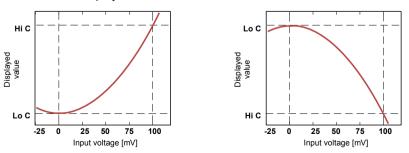


Figure. 9.2 Normal ("Lo C" < "Hi C) and inverted ("Lo C" > "Hi C) characteristic

9.1.3. Square root characteristic

The normalized result is rooted and further conversion is done as for linear characteristic. Conversion is made accordingly with the expression:

$$W = \sqrt{U_n} \times ("Hi C" - "Lo C") + "Lo C",$$

where W means the displayed value.



Showed above expression is not valid when normalized result is negative. In this case ($U_n<0$) the displayed result is equal "Lo C" (see graphs below).

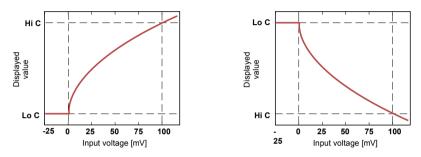


Figure. 9.3 Normal ("Lo C" < "Hi C) and inverted ("Lo C" > "Hi C) characteristic

9.1.4. User defined characteristic

User defined characteristic is defined as set of X-Y points. Number of the points is variable and may be set from 2 to 20 points which make linear segments (see graph and see *Menu "inPt"*). Due to the normalized result U_n , the device computes specific segment, e.g. for characteristic from figure below, and $U_n = 0,65$ the segment between points X = "50.0." and X = "70.0." will be chosen.

Let's mark those points as PL (point low) i PH (point high) - in this example PL= **"50.0,"** and PH = **"70.0."**, and the normalized result U_n for the point PL as U_p (in this example $U_p = U_n(PL) = 0.5$). The displayed result is calculated accordingly to the expression:

$$W = (U_n - U_p) \times \frac{[Y(PH) - Y(PL)]}{[X(PH) - X(PL)]} \times 100 + Y(PL)$$

where Y(PH), X(PH), Y(PL), X(PL) mean values of X and Y coordinates of PH i PL points.



If the normalized result exceeds the user defined characteristic values, then specific utmost segment, defined by two next points, is used for calculations. If characteristic from figure below is used, and if $U_n>1$ then segment defined by points X(PL) = "90.0.", X(PH) = "100.0." will be used.

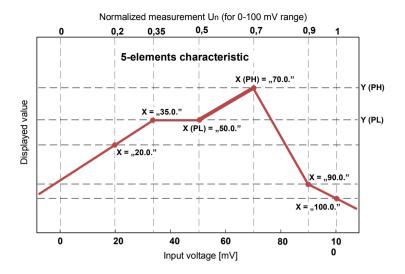


Figure. 9.4 Example of user defined characteristic

9.2. EXAMPLES OF CALCULATIONS

Example 1: Selection of the permissible input range ("100" mode)

If in "**100**" mode the user sets "**Hi r**" = 10,0%, then permissible input voltages range will be equal: $0 \text{ mV} \div 110 \text{ mV}$. Upper border of the range is the result of calculations: 100 mV + 100 mV × 10%.

Example 2: The normalized U_n result calculation

Let the input mode = 0-100 mV. The normalized U_n result is calculated accordingly to the expression on page 33, so if U_{in} = 37.5 mV then 37.5 mV - 0 mV = 37.5 mV, and this result should be divided by the width of input range (100 mV). Finally the normalized result: U_n = 37.5/100 = 0,375.

In case when input voltage exceeds nominal measurement range, calculations are similar. For example if input voltage is equal -9.38 mV then U_n = -9.38/100 \cong -0,0938, and if input voltage is equal 103,13 mV then U_n = 103.13/100 = 1.0313.

Example 3: The linear characteristic

Let the input mode = 0-100 mV, and parameters "Lo C" and "Hi C" equal to -300 and 1200 respectively. The calculations will be done for three different input voltages from example 2.

a) $U_{in} = 37.5 \text{ mV}$ and $U_n = 0.375$

Accordingly to expression on page 34 for linear characteristic: $0,375 \times [1200 - (-300)] \cong 562$ and next, the "Lo C" value is added to the result, so the displayed value: $W \cong 562 + (-300) = 262$

b) U_{in} = -9.38 mV and U_n = -0.0938. W \cong -441.

c) U_{in} = 103.13 mV and U_n = 1.0313. W \cong 1247.

Example 4: The square characteristic

Let the input mode = 0-100 mV, and parameters "Lo C" and "Hi C" equal to -300 and 1200 respectively. The calculations will be done for there different input voltages from example 2.

a) $U_{in} = 37.5 \text{ mV}$ and $U_n = 0.375$ Accordingly to expression on page 34 for square characteristic: $(0,375)^2 \times [1200 - (-300)] \cong 211$. and next, the "Lo C" value is added to the result, so the displayed value:

W ≅ 211 + (-300) = -89

b) U_{in} = -9.38 mV and U_n = -0.0938. W \cong -287.

c) U_{in} = 103.13 mV and U_n = 1.0313. W \cong 1295.

Example 5: The square root characteristic

Let the input mode = 0-100 mV, and parameters **"Lo C"** and **"Hi C"** equal to -300 and 1200 respectively. The calculations will be done for there different input voltages from example 2.

a) U_{in} =37.5 mV and U_n = 0.375 Accordingly to expression on page 35 for square root characteristic: $\sqrt{0,375} \times [1200 - (-300)] \cong 919.$ and next, the **"Lo C"** value is added to the result , so the displayed value: $W \cong 919 + (-300) = 619$

b) U_{in} = -9.38 mV and U_n = -0.0938. , normalized result is negative , so the displayed value is equal to "Lo C" parameter: W \cong "Lo C" = -300.

c)
$$U_{in}$$
 = 103.13 mV and U_n = 1.0313. W \cong 1223.

Example 6: The user defined characteristic

Let the input mode = 0-100 mV, and the user selected the 10 segment characteristic. To do this it is necessary to enter X and Y coordinates of 11 points (see *Menu "inPt"*). The calculations will be done for three different input voltages from example 2, so in calculations some of the segments will be used only.

Let the following points will be given: X1 = "00.0.", Y1 = "-50.0", X2= "10.0.", Y2 = "-30.0", X6 = "30.0.", Y6 = "30.0", X7 = "40.0.", Y7 = "80.0", X10 = "90.0.", Y10 = "900.0", X11 = "100.0.", Y11 = "820.0",

Additionally all other points must to be defined and stored in the device memory.

a) $U_{in} = 37.5 \text{ mV}$ and $U_n = 0.375$

The segment defined by X6 = "**30.0.**" and X7 = "**40.0.**" for this U_n will be selected. Accordingly to expressions given for user defined characteristic (see page 35) X6(PL) = 30, Y6(PL) = 30, X7(PH) = 40, Y7(PH) = 80 and U_p = 0,3, the displayed value :

$$W = (I_n - I_p) \times \frac{[Y(PH) - Y(PL)]}{[X(PH) - X(PL)]} \times 100 + Y(PL) =$$

 $=(0,375-0,3)\times\frac{|80-30|}{|40-30|}\times100+30\simeq67$

b) $U_{in} = -9,38 \text{ mV}$ and $U_n = -0,0938$, because of the normalized U_n value is lower than 0, the segment defined by X1 and X2 will be selected. X1(PL) = 0, Y1(PL) = -50, X2(PH) = 10, Y2(PH) = -30 and $U_p = 0$. For these values the displayed value $W \cong -69$.

c) U_{in} = 103,13 mV and U_n = 1,0313. , because of the normalized U_n value is higher than 1, the segment defined by X10 and X11 will be selected, and X10(PL) = 90, Y10(PL) = 900, X11(PH) = 100, Y11(PH) = 820 and U_p = 0,9 for these values the displayed value W \cong 795.

10. THE MODBUS PROTOCOL HANDLING

Transmission parameters	: 1 start bit, 8 data bits, 1 or 2 stop bit (2 bits are send, 1 and 2 bits
	are accepted when receive), no parity control
Baud rate:	selectable from: 1200 to 115200 bits/second
Transmission protocol:	MODBUS RTU compatible

The device parameters and display value are available via RS-485 interface, as HOLDINGtype registers (numeric values are given in U2 code) of Modbus RTU protocol. The registers (or groups of the registers) can be read by 03h function, and wrote by 06h (single registers) or 10h (group of the registers) accordingly to Modbus RTU specification. Maximum group size for 03h and 10h functions can not exceeds 16 registers (for single frame).



The device interprets the broadcast messages, but then do not sends the answers.

10.1. LIST OF REGISTERS

Register	Write	Range	Register description
01h	No	-999 ÷ 9999	Measurement value (no decimal point)
02h	No	0h, A0h, 60h	The status of the current measurement; 0h - data valid; A0h - top border of the measurement range is exceeded; 60h - bottom border of the measurement range is exceeded;
03h	Yes	0 ÷ 3	"Pnt " parameter in "InPt" menu (decimal point position) 0 - " 0"; 1 - " 0.0"; 2 - " 0.00"; 3 - "0.000"
04h	Yes	see descr.	State of the relays and alarm LED (binary format) (1 - on, 0 - off): 0000000 000e00ba a - relay R1; b - relay R2; e - alarm LED; If written, only a , b bits are important (others are ignored) these bits allows user to control the relays via RS-485 interface
06h	No	-999 ÷ 9999	Peak (drop) value (no decimal point)
10h	Yes	0 ÷ 3	 "tyPE" parameter in "InPt" menu (nominal input range). 0 - 0-60 mV range; 1 - 0-75 mV range; 2 - 0-100 mV range; 3 - 0-150 mV range
11h	Yes	0 ÷ 3	"CHAr" parameter in "InPt" menu (characteristic type) 0 - linear ; 1 - square; 2 - square root; 3 - user defined
12h	Yes	0 ÷ 5	"FiLt" parameter in "InPt" menu (measurement filtering rate)
13h	Yes	0 ÷ 3	"Pnt "parameter in "InPt" menu (the copy of 03h register, decimal point position) 0 - " 0"; 1 - " 0.0"; 2 - " 0.00"; 3 - "0.000"
14h	Yes	-999 ÷ 9999	"Lo C" parameter in "InPt" menu, no decimal point included
15h	Yes	-999 ÷ 9999	"Hi C" parameter in "InPt" menu, no decimal point included
17h	Yes	0 ÷ 99	"Hi r" parameter in "InPt" menu, in 0.1%
20h ²	Yes	0 ÷ 199	Device address
21h	No	20FFh 20FBh	Device identification code (ID) Device identification code (IP65 version)
22h ³	Yes	0 ÷ 7	 "bAud" parameter in "rS" menu (baud rate); 0 - 1200 baud; 1 - 2400 baud; 2 - 4800 baud; 3 - 9600 baud; 4 - 19200 baud; 5 - 38400 baud; 6 - 57600 baud; 7 - 115200 baud
23h⁴	Yes	0 ÷ 1	"mbAc" parameter in "rS" menu (permission to write registers via RS-485 interface); 0 - write denied ; 1 - write allowed

Register	Write	Range	Register description
24h	Yes	see descr.	Parameters of "SECU" menu (binary format (0 - "oFF", 1 - "on"): bit 0 - "A r1" parameter; bit 1 - "A r2" parameter bit 2 - "A r3" parameter; bit 3 - "A r4" parameter
25h	Yes	0 ÷ 5	 "rESP" parameter in "rS" menu (additional response delay); 0 - no additional delay; 1 - "10c" option; 2 - "20c" option; 3 - "50c" option; 4 - "100c" option; 5 - "200c" option;
27h	Yes	0 ÷ 99	 "mbtO" parameter in "rS" menu (maximum delay between received frames); 0 - no delay checking; 1 ÷ 99 - maximum delay expressed in seconds
2Dh	Yes	1 ÷ 8	"bri" parameter (display brightness);1 - the lowest brightness; 8 - the highest brightness
2Eh	Yes	0 ÷ 1	<pre>"SCoL" parameter in "CoL" menu (main colour of display); 0 - green; 1 - red</pre>
2Fh	Yes	0 ÷ 1	<pre>"Edit" parameter (numerical parameters edit mode); 0 - "dig" mode; 1 - "SLid" mode</pre>
30h	Yes	-999 ÷ 9999	"SEtP" parameter in "rEL1" menu, no decimal point included
31h	Yes	-999 ÷ 999	"HySt" parameter in "rEL1" menu, no decimal point included
32h	Yes	0 ÷ 5	<pre>"modE" parameter in "rEL1" menu: 0 - "noAC" mode; 1 - "on" mode; 2 - "oFF" mode; 3 - "in" mode; 4 - "out" mode; 5 - "modb" mode</pre>
33h	Yes	0 ÷ 999	"t on" parameter in "rEL1" menu, expressed in tenth of seconds or tenth of minutes depend on "unit" parameter - register no. 35h)
34h	Yes	0 ÷ 999	"toFF" parameter in "rEL1" menu, expressed in tenth of seconds or tenth of minutes depend on "unit" parameter - register no. 35h)
35h	Yes	0 ÷ 1	<pre>"unit" parameter in "rEL1" menu: 0 - seconds; 1 - minutes</pre>
36h	Yes	0 ÷ 2	"AL" parameter in "rEL1" menu: 0 - no changes; 1 - on; 2 - off
37h	Yes	-999 ÷ 9999	"SEt2" parameter in "rEL1" menu, no decimal point included
38h	Yes	-999 ÷ 9999	"SEtP" parameter in "rEL2" menu, no decimal point included
39h	Yes	-999 ÷ 999	"HySt" parameter in "rEL2" menu, no decimal point included
3Ah	Yes	0 ÷ 5	<pre>"modE" parameter in "rEL2" menu: 0 - "noAC" mode; 1 - "on" mode; 2 - "oFF" mode; 3 - "in" mode; 4 - "out" mode; 5 - "modb" mode</pre>
3Bh	Yes	0 ÷ 999	"t on" parameter in "rEL2" menu, expressed in tenth of seconds or tenth of minutes depend on "unit" parameter - register no. 3Dh)
3Ch	Yes	0 ÷ 999	"toFF" parameter in "rEL2" menu, expressed in tenth of seconds or tenth of minutes depend on "unit" parameter - register no. 3Dh)
3Dh	Yes	0 ÷ 1	"unit" parameter in "rEL2" menu: 0 - seconds; 1 - minutes
3Eh	Yes	0 ÷ 2	"AL" parameter in "rEL2" menu: 0 - no changes; 1 - on; 2 - off
3Fh	Yes	-999 ÷ 9999	"SEt2" parameter in "rEL2" menu, no decimal point included

Register	Write	Range	Register description
50h	Yes	0 ÷ 1	<pre>"modE" parameter in "HOLd" menu (type of detected changes): 0 - peaks; 1 - drops</pre>
51h	Yes	0 ÷ 9999	" PEA " parameter in " HOLd " menu (minimum detectable change, no decimal point included)
52h	Yes	0 ÷ 199	"timE" parameter in "HOLd" menu, maximum peaks' (or drops') display time expressed in seconds
53h	Yes	0 ÷ 1	"HdiS" parameter in "HOLd" menu: 0 - "rEAL" mode ; 1 - "HOLd" mode
54h	Yes	0 ÷ 1	<pre>"H r1" parameter in "HOLd" menu : 0 - "rEAL" mode ; 1 - "HOLd" mode</pre>
55h	Yes	0 ÷ 1	"H r2" parameter in "HOLd" menu: 0 - "rEAL" mode ; 1 - "HOLd" mode
60h	Yes	see descr.	Parameters of "CoL" menu (binary format, 0 - "oFF", 1 - "on"): bit 7 - "C AL" parameter; bit 6 - "C Pr" parameter; bit 1 - "C r2" parameter; bit 0 - "C r1" parameter.
61h	Yes	0 ÷ 1	"CrES" parameter in "CoL" menu (reset of colour indication): 0 - "oFF"; 1 - "on"
62h	Yes	0 ÷ 1	"dir" parameter in "CoL" menu (direction of value changes): 0 - "morE"; 1 - "LESS"
63h	Yes	-999 ÷ 9999	"SEtP" parameter in "CoL" menu, no decimal point included
64h	Yes	-999 ÷ 999	"HySt" parameter in "CoL" menu, no decimal point included
70h⁵	Yes	-999 ÷ 1999	The value of "X " coordinate of point no. 1 of the user defined characteristic, expressed in 0.1%
71h⁵	Yes	-999 ÷ 9999	The value of "Y " coordinate of point no. 1 of the user defined characteristic, no decimal point included
72h⁵ ÷ 95h⁵			Further pairs of $\ _{x}X^{"}$ - $\ _{y}Y^{"}$ coordinates of points no. 2 \div 19 of the user defined characteristic
96h⁵	Yes	-999 ÷ 1999	The value of "X " coordinate of point no. 20 of the user defined characteristic, expressed in 0.1%
97h⁵	Yes	-999 ÷ 9999	The value of "Y" coordinate of point no. 20 of the user defined characteristic, no decimal point included

- after writing to register no 20h the device responds with an "old" address in the message.

2 3 - after writing to register no 22h the device responds with the new baud rate.

4 - the value of the "mbAc" parameter is also connected to write to this register, so it is possible to block a writes, but impossible to unblock writes via RS-485 interface, The unblocking of the writes is possible from menu level only.

5 - the pairs of "X - Y" coordinates may be defined for any free point. The pair is "free" (it means that particular point is not defined) if "X" coordinate of this point is equal 8000h. After writing both X and Y coordinate the point is defined and used in calculation of result. The coordinates of any point can be changed at any time.

10.2. TRANSMISSION ERRORS DESCRIPTION

If an error occurs while write or read of single register, then the device sends an error code according to Modbus RTU specifications (example message no 1).

Error codes:

- **01h** illegal function (only functions 03h, 06h and 10h are available),
- 02h illegal register address
- 03h illegal data value
- **08h** no write permission (see: "mbAc" parameter)
- A0h exceed of upper border of input range
- 60h exceed of lower border of input range

A0h and 60h codes can appear only during reg. 01h is reading by 03h function (read of a single register).

10.3. EXAMPLES OF QUERY/ANSWER FRAMES

Examples apply for device with address 1. All values are represent hexadecimal. **Field description:**

Field description:

ADDR Device address on modbus network

FUNC Function code

REG H,L Starting address (address of first register to read/write, Hi and Lo byte)

COUNT H,L No. of registers to read/write (Hi and Lo byte)

BYTE C Data byte count in answer frame

DATA H,L Data byte (Hi and Lo byte)

CRC L,H CRC error check (Hi and Lo byte)

1. Read of the displayed value (measurement), SRP-73-XC device address = 01h:

ADDR	FUNC	REG	6 H,L	COUN	IT H,L	CRC	L,H
01	03	00	01	00	01	D5	CA

a) The answer (we assume that the measure result is not out of range):

ADDR	FUNC	BYTE C	DATA H,L		DATA H,L CRC L,H	
01	03	02	00	FF	F8	04

DATA H, L - displayed value = 255, no decimal point.

Decimal point position can be read from reg. 03h.

b) The answer (if an error occur):

ADDR	FUNC	ERROR	CRC	L,H
01	83	60	41	18

ERROR - error code = 60h, bottom border of the measurement range is exceeded

2. Read of device ID code

ADDR	FUNC	REG	6 H,L	COUN	IT H,L	CRC	L,H
01	03	00	21	00	01	D4	00

The answer:

ADDR	FUNC	IC BYTE C DATA H,L CRC L,H			L,H	
01	03	02	20	FF	E1	C4

DATA - identification code (20FFh)

3. Change of the device address from 1 to 2 (write to reg. 20h)

ADDR	FUNC	REG	i H,L	DAT	ΑH,L	CRC	L,H
01	06	00	20	00	02	09	C1

DATA H - 0

DATA L - new device address (2)

The answer (the same as the message):

ſ	ADDR	FUNC	REG	6 H,L	DAT	ΑH,L	CRC	L,H
	01	06	00	20	00	02	09	C1

4. Change of baud rate of all devices connected to the net (BROADCAST message).

AD	DR	FUNC	REG	6 H,L	COUN	IT H,L	CRC	L,H
0	0	06	00	22	00	04	29	D2

DATA H - 0

DATA L - 4, new baud rate 19200 baud



Device do not reply to BROADCAST-type messages.

5. Read of the registers 1, 2 and 3 in one message (example of reading a number of registries in one frame):

ADDR	FUNC	REG H,L		COUNT H,L		CRC L,H	
01	03	00	01	00	03	54	0B

COUNT L - the count of being read registers (max.16)

The answer:

ADDR	FUNC	BYTE C	DATA H1,L1		DATA H2,L2		DATA H3,L3		CRC L,H	
01	03	06	00	0A	00	00	00	01	78	B4

DATA H1, L1 - reg. 01h (10 - displayed value "1.0"),

DATA H2, L2 - reg. 02h (0 - no errors),,

DATA H3, L3 - reg. 03h (1 - decimal point position " 0.0").



There is no full implementation of the Modbus Protocol in the device. The functions presented above are available only.

11. DEFAULT AND USER'S SETTINGS LIST

Parameter	Description	Default value	User's value	Desc. page
	Parameters of relay R1 operation	("rEL1" menu)		
SEtP	Relay R1 threshold	20.0		22
SEt2	Relay R1 second threshold	40.0		22
HYSt	Hysteresis of relay R1	0.0		22
modE	Operation mode of relay R1	on		22
t on	Turn on delay of relay R1	0.0		23
toFF	Turn off delay of relay R1	0.0		23
unit	Unit of "t on", "toFF" parameters of relay R1	SEC		23
AL	Reaction for critical situation of relay R1	oFF		23
	Parameters of relay R2 operation	("rEL2" menu)		
SEtP	Relay R2 threshold	40.0		22
SEt2	Relay R2 second threshold	60.0		22
HYSt	Hysteresis of relay R2	0.0		22
modE	Operation mode of relay R2	on		22
t on	Turn on delay of relay R2	0.0		23
toFF	Turn off delay of relay R2	0.0		23
unit	Unit of "t on", "toFF" parameters of relay R2	SEC		23
AL	Reaction for critical situation of relay R2	oFF		23
	Configuration of measurement inpu	ıt ("inPt" menu)		
tYPE	Input mode	"60"		24
CHAr	Conversion characteristic mode	Lin		24
FiLt	Filtering ratio	0		24
Pnt	Decimal point position	0.0		24
Lo C	Minimum displayed value (for nominal range)	000.0		24
Hi C	Maximum displayed value (for nominal range)	100.0		24
Hi r	Extension of the top of the nominal input range	5.0 (%)		25
	Display parameters			
bri	Display brightness	bri6		26
	Signalization via colour of the displa	y ("CoL" menu)		
SCoL	Basic colour of the display	grEE		26
C r1	Change display colour after R1 is activated	oFF		26
C r2	Change display colour after R2 is activated	oFF		26

Parameter	Description	Default value	User's value	Desc. page	
C AL	Change display colour after alarm occurs	oFF		27	
C Pr	Enable additional threshold while signalisation via colour	oFF		27	
dir	The direction of result changes activating change of display colour	morE		27	
SEtP	Threshold of display colour control	500		27	
HySt	Hysteresis of display colour control	0		27	
CrES	Enable the use of local keyboard for acknowledgement of display colour signalisation.	oFF		27	
	Configuration of peaks detection function	n ("HOLd" men	iu)		
modE	Kind of detected changes	norm		28	
PEA	Minimum detected change	0.0		28	
timE	Maximum time of peak displaying	0.0		28	
HdiS	The type of displayed value	HOLd		28	
Hr1	Source of relay R1, and LED R1 control	rEAL		28	
H r2	Source of relay R2, and LED R2 control	rEAL		28	
	Settings of access to the configuration param	neters ("SECu"	menu)		
A r1	Permission to changes of relay R1 threshold without of the user password knowledge	on		28	
A r2	Permission to changes of relay R2 threshold without of the user password knowledge	on		28	
	RS 485 interface configuration (m	ienu "rS")			
Addr	Device address	0		28	
bAud	Baud rate	9.6		29	
mbAc	Permission to changes of configuration registers	on		29	
mbtO	Maximum delay between received messages	0		29	
rESP	Additional delay of answer transmission	Std		29	
	Configuration of numerical parame	ters edition			
Edit	Numerical parameters edit mode	dig		29	





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